

BAB V

KESIMPULAN DAN SARAN

A. Kesimpulan

1. Berdasarkan masalah yang diajukan tentang bagaimanakah kondisi *apron floodlight* di Bandar Udara Internasional Yogyakarta apakah sudah menggunakan kontrol dari jarak jauh, dari hasil pengujian rancangan alat ini dapat di gunakan untuk memonitor dan mengontrol *floodlight* di Bandar Udara Internasional Yogyakarta.
2. Rancangan *system* kontrol dan monitoring *apron floodlight* di Bandar Udara Internasional Yogyakarta menggunakan teknologi IoT dengan sensor ACS712 dan BH1750 yang berguna untuk monitoring *real-time* arus listrik dan intensitas cahaya serta kontrol jarak jauh melalui *smartphone* atau komputer dan alat ini dapat memonitor dan mengendalikan *floodlight* di Bandara Udara Internasioanl Yogyakarta.

B. Saran

1. Alat ini dapat di implementasikan untuk mengontrol *floodlight* di bandar udara internasional Yogyakarta *prototype* ini dapat dikembangkan dalam sistem kontrol *floodlight* secara otomatis. Seperti menggunakan sensor *infrared* atau menggunakan *espcam* dalam hal pengoperasian *apron floodlight*.
2. *Prototype* ini dapat diaplikasikan dengan memaksimalkan kondisi jaringan radio yang dapat berfungsi di tempat tanpa hambatan dari sinyal lain nya sehingga pengoperasian secara otomatis dapat bekerja dengan maksimal sesuai dengan kondisi lingkungan sekitar serta pemancar sinyal yang harus berada di tempat yang tinggi.
3. Sistem kontrol dapat ditambahkan dengan menambahkan kontrol motor untuk menurunkan serta menaikkan *floodlight*.

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LAMPIRAN



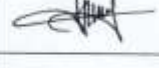

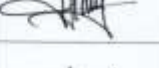



1. LAMPIRAN 1 LEMBAR PEMBIMBING 1




POLITEKNIK PENERBANGAN PALEMBANG
PROGRAM STUDI
TEKNOLOGI REKAYASA BANDAR UDARA
PROGRAM SARJANA TERAPAN

LEMBAR BIMBINGAN TUGAS AKHIR
TAHUN AKADEMIK 2023/2024

Nama Taruna : FALHREGI NUBRANO
 NIT : 56192010007
 Course : TRDI A
 Judul TA : RANCANGAN SISTEM MONITORING DAN KONTROL OTOMATIS PADA FLOODLIGHT BERBASIS IOT DI BANDAR UDARA INTERNASIONAL YOGYAKARTA
 Dosen Pembimbing : Johnny Emiyani S.Si.T., M.Si.


No	Tanggal	Uraian	Paraf Pembimbing
1	21/05/24	Perbaiki Proposal Judul.	
2	3/6/24	- Penambahan Pehelitan yg relevan. - Perbaikan Penulisan.	
3	21/6/24	- Masukan Gambar - Kardan Power . - Check Panduan .	
4	27/6/24	- Penambahan indikator ds alat .	
5	11/7/24	- check kembali Penulisan (visualisasi)	
6	15/7/24	- Validasi alat ds .	
7	16/7/24	- Power Point siday ds .	
8	17/7/24	- Lanjut siday TA .	

Mengetahui,
 Ketua Program Studi
 Teknologi Rekayasa Bandar Udara




M. Indra Martadinata, S.ST., M.Si.
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Dosen Pembimbing



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2. LAMPIRAN 2 LEMBAR PEMBIMBING 2



POLITEKNIK PENERBANGAN PALEMBANG
PROGRAM STUDI
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PROGRAM SARJANA TERAPAN


LEMBAR BIMBINGAN TUGAS AKHIR
TAHUN AKADEMIK 2023/2024


Nama Taruna : FACHREGI NUGROHO
NIT : 56192010007
Course : TRBU DI AIRA
Judul TA : RANCANGAN SISTEM MONITORING DAN KONTROL OTOMATIS PADA FLIGHTLIGHT BERBASIS IOT DI BANDAR UDARA INTERNASIONAL YOGYAKARTA
Dosen Pembimbing : (R. ASEP MUHAMMAD SOLEH, S.SiT., ST., M.Pd.

No	Tanggal	Uraian	Paraf Pembimbing
1	21-05-2024	- Perbaikan Situs; - Bab Pendahuluan dan Isi dari Situs; - Manfaat perancangan aplikasi; Perancangan; - Sistem monitoring bandara; - Sistem monitoring perlintasan; - Situs;	
2	31-05-2024	- Perum bahan-bahan yang digunakan	
3	20-06-2024	- Perambutan Gambar - Pengambilan Pemanduan	
4	1-07-2024	- Perumbuhan Indikator di Aplikasi	
5	3-07-2024	- Validasi wiring alur oke	
6	5-07-2024	- bimbingan bab V hasil dan kesimpulan	
7	8-07-2024	- Power point Sidung	
8	11-07-2024	Dapat di lanjutkan ujian TA.	

Mengetahui,
Ketua Program Studi
Teknologi Rekayasa Bandar Udara

Dosen Pembimbing


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NIP. 19750621 199803 1 002





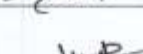
3. LAMPIRAN 3 FORM PENGUJIAN ALAT

FORM PENGUJIAN ALAT TUGAS AKHIR

Judul TA	RANCANGAN SISTEM MONITORING DAN KONTROL OTOMATIS PADA FLOODLIGHT BERBASIS IOT DI BANDAR UDARA INTERNASIONAL YOGYAKARTA
Nama Taruna	Fachregi Nugroho
Course	TR01A
Tanggal pelaksanaan	

1) Deskripsi Pengujian

Setelah design prototipe selesai, komponen-komponen yang diperlukan telah di uji dan seluruh program, komponen selesai di satukan dalam bentuk prototipe kontrol dan monitoring floodlight bekerja dengan baik atau tidak. Berikut adalah kriteria yang akan di uji:

No	Pengujian Prototipe	Hasil pengujian	Paraf pembimbing
1	Rancangan dapat bekerja secara manual dan otomatis	berhasil	
2	Sensor ACS712 Pada Prototipe dapat bekerja dengan benar	berhasil	
3	Rancangan manual dioperasikan dengan <i>selektor Switch</i> dapat bekerja dengan normal.	berhasil	
4	Sensor BH1750 Pada Prototipe dapat bekerja dengan benar	berhasil	
5	Prototipe dirancang menggunakan kendali berbasis <i>web</i> dengan menggunakan aplikasi <i>Visual Studio code</i> di <i>smartphone android</i> dan <i>PC</i> dapat bekerja dengan normal.	berhasil	

PEMBIMBING



Johny Emiyani, S.Si.T., M.Si.
Penata (III/c)
NIP. 19811005 200912 1 003

4. LAMPIRAN 4 DATA SHEET ACS712



ACS712

Fully Integrated, Hall-Effect-Based Linear Current Sensor IC with 2.4 kV_{RMS} Isolation and a Low-Resistance Current Conductor

FEATURES AND BENEFITS

- Low-noise analog signal path
- Device bandwidth is set via the new FILTER pin
- 5 μ s output rise time in response to step input current
- 80 kHz bandwidth
- Total output error 1.5% at $T_A = 25^\circ\text{C}$
- Small footprint, low-profile SOIC-8 package
- 1.2 m Ω internal conductor resistance
- 2.4 kV_{RMS} minimum isolation voltage from pins 1-4 to pins 5-8
- 5.0 V, single supply operation
- 66 to 185 mV/A output sensitivity
- Output voltage proportional to AC or DC currents
- Factory-trimmed for accuracy
- Extremely stable output offset voltage
- Nearly zero magnetic hysteresis
- Ratio-metric output from supply voltage



TUV America
Certificate Number
UBV 15 05 54214 03B
CB 13 06 94214 03B

PACKAGE: 8-Lead SOIC (suffix LC)



Not to scale

DESCRIPTION

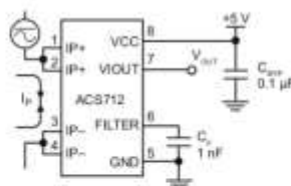
The Allegro™ ACS712 provides economical and precise solutions for AC or DC current sensing in industrial, commercial, and communications systems. The device package allows for easy implementation by the customer. Typical applications include motor control, load detection and management, switch-mode power supplies, and overcurrent fault protection. The device is not intended for automotive applications.

The device consists of a precise, low-offset, linear Hall circuit with a copper conduction path located near the surface of the die. Applied current flowing through this copper conduction path generates a magnetic field which the Hall IC converts into a proportional voltage. Device accuracy is optimized through the close proximity of the magnetic signal to the Hall transducer. A precise, proportional voltage is provided by the low-offset, copper-stabilized BiCMOS Hall IC, which is programmed for accuracy after packaging.

The output of the device has a positive slope ($\rightarrow V_{\text{OUT}}(Q)$) when an increasing current flows through the primary copper conduction path (from pins 1 and 2, to pins 3 and 4), which is the path used for current sampling. The internal resistance of this conductive path is 1.2 m Ω typical, providing low power loss. The thickness of the copper conductor allows survival of

Continued on the next page...

Typical Application



Application 1. The ACS712 outputs an analog signal, V_{OUT} that varies linearly with the uni- or bi-directional AC or DC primary sampled current, I_p , within the range specified. C_f is recommended for noise management, with values that depend on the application.

ACS712**Fully Integrated, Hall-Effect-Based Linear Current Sensor IC
with 2.4 kV_{RMS} Isolation and a Low-Resistance Current Conductor****ISOLATION CHARACTERISTICS**

Characteristic	Symbol	Notes	Rating	Unit
Withstand Voltage ⁽¹⁾	V _{ISO}	Agency rated for 60 seconds per UL 62368-1 (edition 3)	2400	V _{RMS}
Working Voltage for Basic Isolation	V _{WVBI}	Maximum approved working voltage for basic (single) isolation according to UL 62368-1 (edition 3)	420	V _{WV} or V _{DC}
			297	V _{RMS}
Impulse Withstand Voltage	V _{AVULSI}	Tested ±5 pulses at 2minute in compliance to IEC 61000-4-5, 1.2 µs (rise) 50 µs (width)	4000	V _{PK}
Clearance	D _{CL}	Minimum distance through air from IP leads to signal leads	4	mm
Creepage	D _{CP}	Minimum distance along package body from IP leads to signal leads	4	mm
Distance Through Insulation	DTI	Minimum internal distance through insulation	63	µm
Comparative Tracking Index	CTI	Material Group II	400 to 599	V

⁽¹⁾ 100% Production-tested for 1 second in accordance with UL 62368-1 (edition 3)

Parameter	Specification
Fire and Electric Shock	CAN/CSA-C22.2 No. 60950-1-03 UL 60950-1:2003 EN 60950-1:2001

ACS712

Fully Integrated, Hall-Effect-Based Linear Current Sensor IC with 2.4 kV_{RMS} Isolation and a Low-Resistance Current Conductor

DESCRIPTION (continued)

the device at up to 5× overcurrent conditions. The terminals of the conductive path are electrically isolated from the signal leads (pins 5 through 8). This allows the ACS712 to be used in applications requiring electrical isolation without the use of opto-isolators or other costly isolation techniques.

The ACS712 is provided in a small, surface mount SOIC8 package. The leadframe is plated with 100% matte tin, which is compatible with standard lead (Pb) free printed circuit board assembly processes. Internally, the device is Pb-free, except for flip-chip high-temperature Pb-based solder balls, currently exempt from RoHS. The device is fully calibrated prior to shipment from the factory.

SELECTION GUIDE

Part Number	Packing [1]	T _A (°C)	Current Sensing Range, I _p (A)	Sensitivity, Sens (Typ) (mV/A)
-S VARIANT [2]				
ACS712ELCTR-20A-S	Tape and reel, 3000 pieces/reel	-40 to 85	±20	100
ACS712ELCTR-30A-S	Tape and reel, 3000 pieces/reel	-40 to 85	±30	66
-T VARIANT [3]				
ACS712ELCTR-05B-T	Tape and reel, 3000 pieces/reel	-40 to 85	±5	185
ACS712ELCTR-20A-T	Tape and reel, 3000 pieces/reel	-40 to 85	±20	100
ACS712ELCTR-30A-T	Tape and reel, 3000 pieces/reel	-40 to 85	±30	66

[1] Contact Allegro for additional packing options.

[2] -S denotes the lead-free construction with tin-silver based solder bumps.

[3] -T denotes Pb-contained construction with Pb-based solder bumps. Operating performance of -T and -S devices are identical. -T devices are RoHS compliant using allowed exemptions provided in Annex III and IV of Directive 2011/65/EU (Exemptions 7(a), 15, 15(a), as applicable).

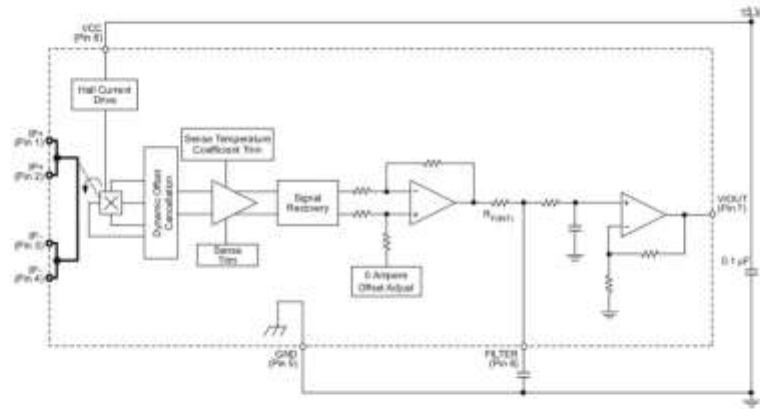
ABSOLUTE MAXIMUM RATINGS

Characteristic	Symbol	Notes	Rating	Units
Supply Voltage	V _{CC}		8	V
Reverse Supply Voltage	V _{RECC}		-0.1	V
Output Voltage	V _{OUT}		8	V
Reverse Output Voltage	V _{REOUT}		-0.1	V
Output Current Source	I _{OUT(SOURCE)}		3	mA
Output Current Sink	I _{OUT(SINK)}		10	mA
Overcurrent Transient Tolerance	I _p	1 pulse, 100 ns	100	A
Nominal Operating Ambient Temperature	T _A	Range E	-40 to 85	°C
Maximum Junction Temperature	T _{J(MAX)}		185	°C
Storage Temperature	T _{STG}		-65 to 170	°C

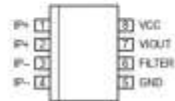
ACS712

Fully Integrated, Hall-Effect-Based Linear Current Sensor IC
with 2.4 kV_{RMS} Isolation and a Low-Resistance Current Conductor

FUNCTIONAL BLOCK DIAGRAM



Pinout Diagram



Terminal List

Number	Name	Description
1 and 2	IP+	Terminals for current being sampled; fused internally
3 and 4	IP-	Terminals for current being sampled; fused internally
5	GND	Signal ground terminal
6	FILTER	Terminal for external capacitor that sets bandwidth
7	VOUT	Analog output signal
8	VCC	Device power supply terminal

ACS712

Fully Integrated, Hall-Effect-Based Linear Current Sensor IC with 2.4 kV_{RMS} Isolation and a Low-Resistance Current Conductor

COMMON OPERATING CHARACTERISTICS [1]: Over full range of T_A , $C_F = 1$ nF, and $V_{CC} = 5$ V, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ.	Max.	Units
ELECTRICAL CHARACTERISTICS						
Supply Voltage	V_{CC}		4.5	5.0	5.5	V
Supply Current	I_{CC}	$V_{CC} = 5.0$ V, output open	–	10	13	mA
Output Capacitance Load	C_{LOAD}	V _{OUT} to GND	–	–	10	nF
Output Resistive Load	R_{LOAD}	V _{OUT} to GND	4.7	–	–	kΩ
Primary Conductor Resistance	$R_{PRIMARY}$	$T_A = 25^\circ\text{C}$	–	1.2	–	mΩ
Rise Time	t_r	$I_P = I_P(\text{max})$, $T_A = 25^\circ\text{C}$, $C_{OUT} = \text{open}$	–	3.5	–	μs
Frequency Bandwidth	f	–3 dB, $T_A = 25^\circ\text{C}$, I_P is 10 A peak-to-peak	–	80	–	kHz
Nonlinearity	E_{NL}	Over full range of I_P	–	1.5	–	%
Symmetry	E_{SYM}	Over full range of I_P	98	100	102	%
Zero Current Output Voltage	$V_{OUT(0)}$	Bidirectional, $I_P = 0$ A, $T_A = 25^\circ\text{C}$	–	$V_{CC} * 0.5$	–	V
Power-On Time	t_{PO}	Output reaches 90% of steady-state level, $T_J = 25^\circ\text{C}$, 20 A present on leadframe	–	35	–	μs
Magnetic Coupling [2]			–	12	–	G/A
Internal Filter Resistance [3]	R_{FILT}		–	1.7	–	kΩ

[1] Device may be operated at higher primary current levels, I_P , and ambient, T_A , and internal leadframe temperatures, T_L , provided that the Maximum Junction Temperature, $T_{J(\text{max})}$, is not exceeded.

[2] $I_G = 0.1$ mT

[3] R_{FILT} forms an RC circuit via the FILTER pin.

COMMON THERMAL CHARACTERISTICS [1]

Characteristic	Symbol	Test Conditions	Min.	Typ.	Max.	Units
Operating Internal Leadframe Temperature	T_L	E range	–40	–	85	$^\circ\text{C}$
Characteristic	Symbol	Test Conditions		Value	Units	
Junction-to-Lead Thermal Resistance [2]	$R_{\theta JL}$	Mounted on the Allegro A5EK 712 evaluation board		5	$^\circ\text{C/W}$	
Junction-to-Ambient Thermal Resistance	$R_{\theta JA}$	Mounted on the Allegro 85-0322 evaluation board, includes the power consumed by the board		23	$^\circ\text{C/W}$	

[1] Additional thermal information is available on the Allegro website.

[2] The Allegro evaluation board has 1500 mm² of 2 oz. copper on each side, connected to pins 1 and 2, and to pins 3 and 4, with thermal vias connecting the layers. Performance values include the power consumed by the PCB. Further details on the board are available from the Frequently Asked Questions document on our website. Further information about board design and thermal performance also can be found in the Applications Information section of this datasheet.

5. LAMPIRAN 5 DATA SHEET BH1750



Ambient Light Sensor IC Series

Digital 16bit Serial Output Type Ambient Light Sensor IC



BH1750FVI

No.11045EDT01

●Descriptions

BH1750FVI is a digital Ambient Light Sensor IC for I²C bus interface. This IC is the most suitable to obtain the ambient light data for adjusting LCD and Keypad backlight power of Mobile phone. It is possible to detect wide range at High resolution, (1 - 85535 lx).

●Features

- 1) I²C bus interface (f / s Mode Support)
- 2) Spectral responsibility is approximately human eye response
- 3) Illuminance to Digital Converter
- 4) Wide range and High resolution. (1 - 85535 lx)
- 5) Low Current by power down function
- 6) 50Hz / 60Hz Light noise reject-function
- 7) 1.8V Logic input interface
- 8) No need any external parts
- 9) Light source dependency is little. (ex. Incandescent Lamp, Fluorescent Lamp, Halogen Lamp, White LED, Sun Light)
- 10) It is possible to select 2 type of I²C slave-address.
- 11) Adjustable measurement result for influence of optical window
(It is possible to detect min. 0.11 lx, max. 100000 lx by using this function.)
- 12) Small measurement variation (+/- 20%)
- 13) The influence of infrared is very small.

●Applications

Mobile phone, LCD TV, NOTE PC, Portable game machine, Digital camera, Digital video camera, PDA, LCD display

●Absolute Maximum Ratings

Parameter	Symbol	Ratings	Units
Supply Voltage	V _{max}	4.5	V
Operating Temperature	T _{opr}	-40~85	°C
Storage Temperature	T _{stg}	-40~100	°C
SDA Sink Current	I _{max}	7	mA
Power Dissipation	P _d	260 ⁽¹⁾	mW

(1) 70mm × 70mm × 1.6mm glass epoxy board. Derating is done at 3.47mW/°C for operating above Ta=25°C

●Operating Conditions

Parameter	Symbol	Ratings			Units
		Min.	Typ.	Max.	
V _{CC} Voltage	V _{CC}	2.4	3.0	3.6	V
I ² C Reference Voltage	V _{ovt}	1.65	-	V _{CC}	V

●Electrical Characteristics (Vcc = 3.0V, DVI = 3.0V, Ta = 25°C, unless otherwise noted)

Parameter	Symbol	Limits			Units	Conditions
		Min.	Typ.	Max.		
Supply Current	icc1	—	120	190	μA	Ev = 100 lx ^{#1}
Powerdown Current	icc2	—	0.01	1.0	μA	No input Light
Peak Wave Length	λp	—	560	—	nm	
Measurement Accuracy	S/A	0.96	1.2	1.44	times	Sensor out / Actual lx EV = 1000 lx ^{#1, #2}
Dark (0 lx) Sensor out	S0	0	0	3	count	H-Resolution Mode ^{#3}
H-Resolution Mode Resolution	nR	—	1	—	lx	
L-Resolution Mode Resolution	nL	—	4	—	lx	
H-Resolution Mode Measurement Time	tHR	—	120	180	ms	
L-Resolution Mode Measurement Time	tLR	—	16	24	ms	
Incandescent / Fluorescent Sensor out ratio	rIF	—	1	—	times	EV = 1000 lx
ADDR Input 'H' Voltage	V _{AH}	0.7 * VCC	—	—	V	
ADDR Input 'L' Voltage	V _{AL}	—	—	0.3 * VCC	V	
DVI Input 'L' Voltage	V _{DVL}	—	—	0.4	V	
SCL, SDA Input 'H' Voltage 1	V _{IH1}	0.7 * DVI	—	—	V	DVI ≥ 1.8V
SCL, SDA Input 'H' Voltage 2	V _{IH2}	1.26	—	—	V	1.65V ≤ DVI < 1.8V
SCL, SDA Input 'L' Voltage 1	V _{IL1}	—	—	0.3 * DVI	V	DVI ≥ 1.8V
SCL, SDA Input 'L' Voltage 2	V _{IL2}	—	—	DVI - 1.26	V	1.65V ≤ DVI < 1.8V
SCL, SDA, ADDR Input 'H' Current	I _{IH}	—	—	10	μA	
SCL, SDA, ADDR Input 'L' Current	I _{IL}	—	—	10	μA	
I ² C SCL Clock Frequency	f _{SCL}	—	—	400	kHz	
I ² C Bus Free Time	t _{BUF}	1.3	—	—	μs	
I ² C Hold Time (repeated) START Condition	t _{H0STA}	0.6	—	—	μs	
I ² C Set up time for a Repeated START Condition	t _{SUSTA}	0.6	—	—	μs	
I ² C Set up time for a Repeated STOP Condition	t _{SUSTD}	0.6	—	—	μs	
I ² C Data Hold Time	t _{H0DAT}	0	—	0.9	μs	
I ² C Data Setup Time	t _{SUDAT}	100	—	—	ns	
I ² C 'L' Period of the SCL Clock	t _{LOW}	1.3	—	—	μs	
I ² C 'H' Period of the SCL Clock	t _{HIGH}	0.6	—	—	μs	
I ² C SDA Output 'L' Voltage	V _{OL}	0	—	0.4	V	I _{OL} = 3 mA

#1 White LED is used as optical source.

#2 Measurement Accuracy typical value is possible to change "1" by "Measurement result adjustment function".

#3 Use H-resolution mode or H-resolution mode2 if dark data (less than 10 lx) is need.

●Reference Data

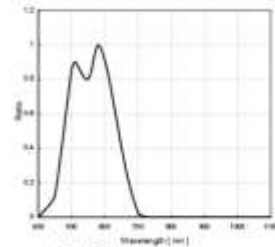


Fig.1 Spectral Response

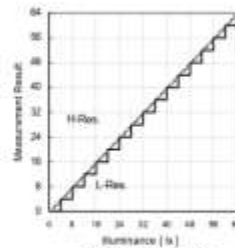


Fig.2 Illuminance - Measurement Result 1

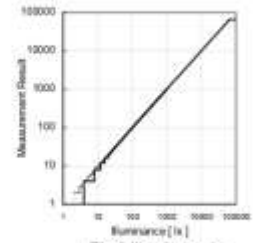


Fig.3 Illuminance - Measurement Result 2

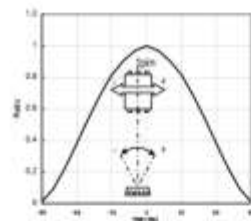


Fig.4 Directional Characteristics 1

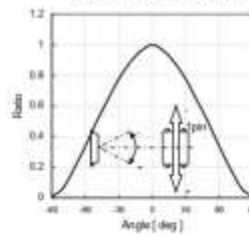


Fig.5 Directional Characteristics 2

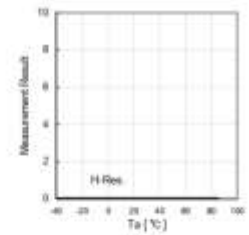


Fig.6 Dark Response

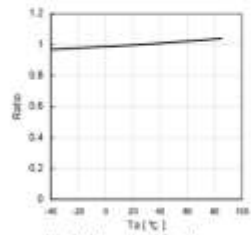


Fig.7 Measurement Accuracy Temperature Dependency

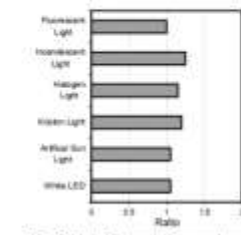


Fig.8 Light Source Dependency (Fluorescent Light is set to "1")

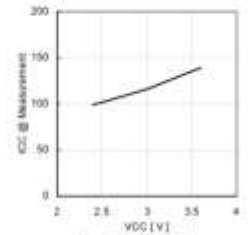


Fig.9 VCC - ICC (During measurement)

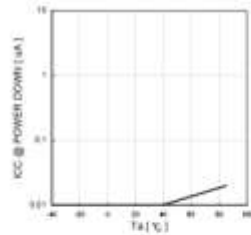


Fig.10 VCC - ICC@0 Lx (POWER DOWN)

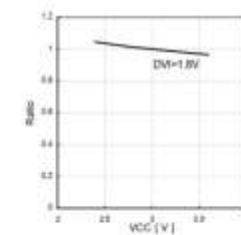


Fig.11 Measurement Result VCC Dependency

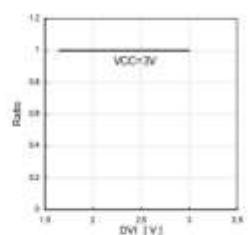
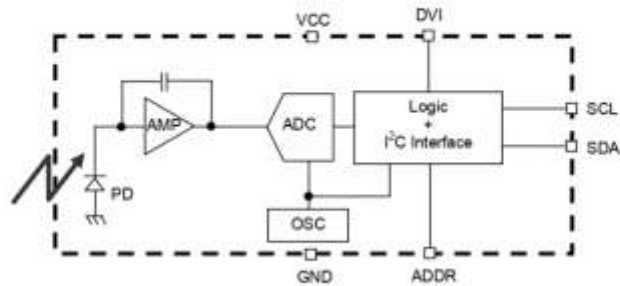


Fig.12 Measurement Result DVI Dependency

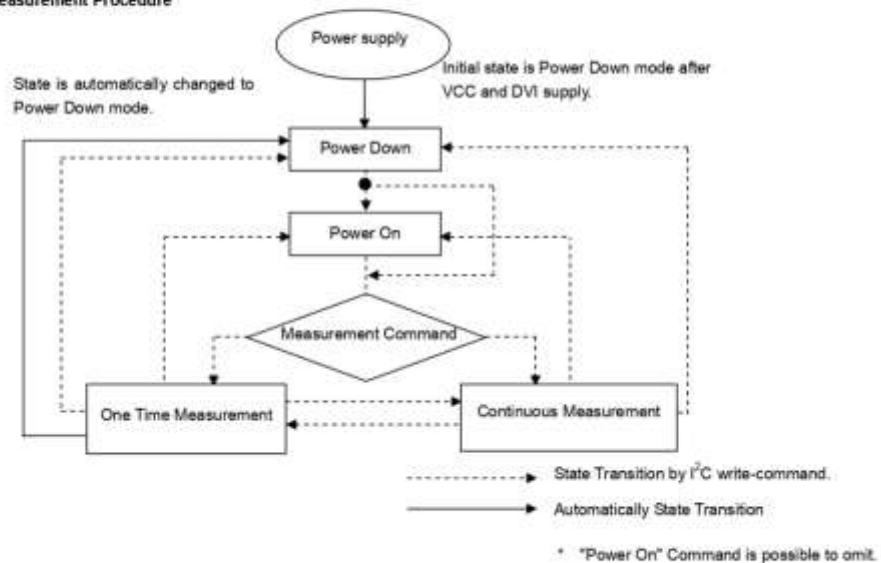
●Block Diagram



●Block Diagram Descriptions

- PD
Photo diode with approximately human eye response.
- AMP
Integration-OPAMP for converting from PD current to Voltage.
- ADC
AD converter for obtaining Digital 16bit data.
- Logic + I²C Interface
Ambient Light Calculation and I²C BUS Interface. It is including below register.
Data Register → This is for registration of Ambient Light Data. Initial Value is "0000_0000_0000_0000".
Measurement Time Register → This is for registration of measurement time. Initial Value is "0100_0101".
- OSC
Internal Oscillator (typ. 320kHz). It is CLK for internal logic.

●Measurement Procedure



●Instruction Set Architecture

Instruction	Opcode	Comments
Power Down	0000_0000	No active state.
Power On	0000_0001	Waiting for measurement command.
Reset	0000_0111	Reset Data register value. Reset command is not acceptable in Power Down mode.
Continuously H-Resolution Mode	0001_0000	Start measurement at 1lx resolution. Measurement Time is typically 120ms.
Continuously H-Resolution Mode2	0001_0001	Start measurement at 0.5lx resolution. Measurement Time is typically 120ms.
Continuously L-Resolution Mode	0001_0011	Start measurement at 4lx resolution. Measurement Time is typically 16ms.
One Time H-Resolution Mode	0010_0000	Start measurement at 1lx resolution. Measurement Time is typically 120ms. It is automatically set to Power Down mode after measurement.
One Time H-Resolution Mode2	0010_0001	Start measurement at 0.5lx resolution. Measurement Time is typically 120ms. It is automatically set to Power Down mode after measurement.
One Time L-Resolution Mode	0010_0011	Start measurement at 4lx resolution. Measurement Time is typically 16ms. It is automatically set to Power Down mode after measurement.
Change Measurement time (High bit)	01000_MT[7,6,5]	Change measurement time. Ⓢ Please refer "adjust measurement result for influence of optical window"
Change Measurement time (Low bit)	011_MT[4,3,2,1,0]	Change measurement time. Ⓢ Please refer "adjust measurement result for influence of optical window"

Ⓢ Don't input the other opcode.

●Measurement mode explanation

Measurement Mode	Measurement Time	Resolution
H-resolution Mode2	Typ. 120ms.	0.5 lx
H-Resolution Mode	Typ. 120ms.	1 lx.
L-Resolution Mode	Typ. 16ms.	4 lx.

We recommend to use H-Resolution Mode.

Measurement time (integration time) of H-Resolution Mode is so long that some kind of noise(including in 50Hz / 60Hz noise) is rejected. And H-Resolution Mode is 1 lx resolution so that it is suitable for darkness (less than 10 lx)
H-resolution mode2 is also suitable to detect for darkness.

●Explanation of Asynchronous reset and Reset command "0000_0111"

1) Asynchronous reset

All registers are reset. It is necessary on power supply sequence. Please refer "Timing chart for VCC and DVI power supply sequence" in this page. It is power down mode during DVI = 'L'.

2) Reset command

Reset command is for only reset illuminance data register. (reset value is '0') It is not necessary even power supply sequence. It is used for removing previous measurement result. This command is not working in power down mode, so that please set the power on mode before input this command.

6. LAMPIRAN 6 FOTO KALIBRASI KOMPONEN





7. LAMPIRAN 7 VALIDASI WIRING DAN ALAT








FORM PENGUJIAN ALAT TUGAS AKHIR

Judul TA	RANCANGAN SISTEM MONITORING DAN KONTROL OTOMATIS PADA FLOODLIGHT BERBASIS IOT DI BANDAR UDARA INTERNASIONAL YOGYAKARTA
Nama Taruna	Fachregi Nugroho
Course	TR01A
Tanggal pelaksanaan	

1) Deskripsi Pengujian

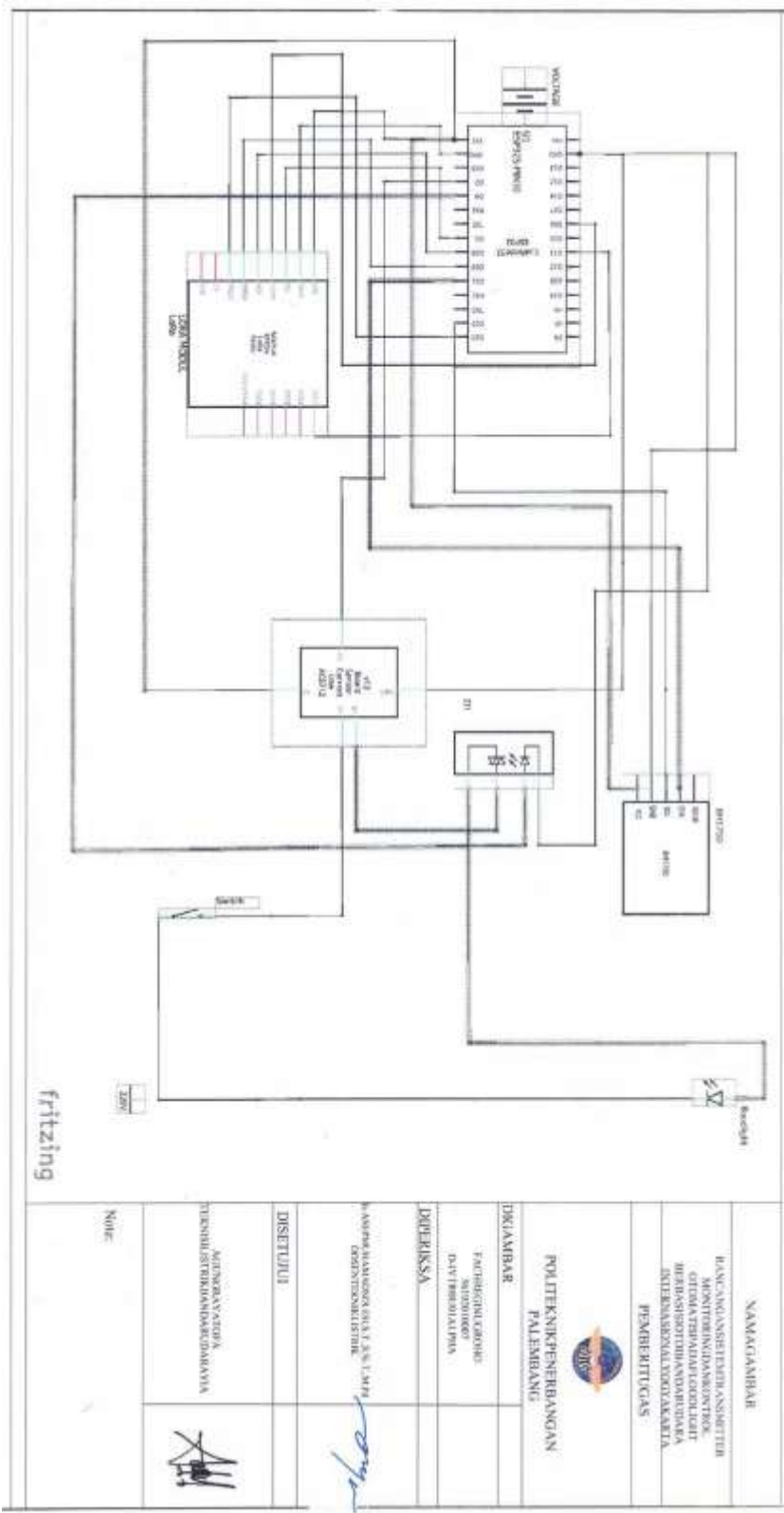
Setelah design prototipe selesai, komponen-komponen yang diperlukan telah di uji dan seluruh program, komponen selesai di satukan dalam bentuk prototipe kontrol dan monitoring floodlight bekerja dengan baik atau tidak. Berikut adalah kriteria yang akan di uji:

No	Pengujian Prototipe	Hasil pengujian	Paraf pembimbing
1	Rancangan dapat bekerja secara manual dan otomatis	berhasil	
2	Sensor ACS712 Pada Prototipe dapat bekerja dengan benar	berhasil	
3	Rancangan manual dioperasikan dengan <i>selektor Switch</i> dapat bekerja dengan normal.	berhasil	
4	Sensor BH1750 Pada Prototipe dapat bekerja dengan benar	berhasil	
5	Prototipe dirancang menggunakan kendali berbasis <i>web</i> dengan menggunakan aplikasi <i>Visual Studio code</i> di <i>smartphone android</i> dan <i>PC</i> dapat bekerja dengan normal.	berhasil	

PEMBIMBING



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Penata (III/c)
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fritzing

<p>NAMA/GAMBAR</p> <p>BANCAN ANSHER DEDAH ANSHER TER MONITORING DAN SISTEM OTOMATISASI ALAT KUKUS RUMAH BERSIH SOTER DAN BAHAN BAKU INTERAKSI DAN LOGIKA KAKI PEMERIKSA</p>	
<p>DIKIAMBAR</p> <p>POLITEKNIK PERBANGUNAN PALHARANG</p>	
<p>DIKERJAKAN</p> <p>FAKULTAS TEKNIK INFORMATIKA DATA BERKUALITAS</p>	
<p>DISERTUJUKAN</p> <p>KELOMPOK 1 1. NAMA 2. NAMA 3. NAMA</p>	
<p>NOTE</p>	